

The Multi-engine ASP Solver ME-ASP: Progress Report

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- The number of real-life ASP applications is significantly increasing; thus, efficient ASP systems are needed
- It is well-known that, on empirically hard problems, there is rarely a “global” best algorithm
- Instead, different algorithms perform well on different problem domains/instances (Rice, 1976)
- This fact can be taken as an advantage, by exploiting machine learning techniques

Machine learning techniques for solving empirically “hard” (ASP) problems range over:

- multi-engine approach (ME-ASP)
 - chooses among its engines/solvers the one which is more likely to yield optimal results
- portfolio approach (CLASPFOLIO ver. 1)
 - (multi-engine +) allows for changing online the engine employed (or, to change engine’s configuration)
- algorithm configuration/scheduling, parameter tuning (ASPeed)
 - finds parameter settings (or, *configurations*) of an engine for which the empirical performance on a given set of problem instances is “optimized”, and/or computes an ordering on the engines to be run (*schedule*)
- (Balduccini, 2011) (DORS)
 - selects offline a heuristic ordering to be used in an engine when solving other programs from the same domain

In these contexts, some ingredients are often considered:

- a set of “features” that represent several aspects of a problem
- one or more engines on top of which building the approach
- a training set on which learning the decision policy
- a test set on which the approach is evaluated

ASP seems to be good venue for applying a multi-engine approach:

- many ASP systems, featuring different techniques
- many ASP domains and instances (thanks to competitions), on which training and testing the approach

A multi-engine approach for Answer Set Programming (ME-ASP) that:

- 1 extracts syntactic cheap-to-compute features on a *training set* of instances
- 2 selects a pool of ASP solvers that are representative of the state of the art
- 3 learns a decision policy with a classifier, based on the features computed and the performances of the selected solvers on the training instances
- 4 applies the policy to instances in a *test set*

ME-ASP (MPR, 2014a) shows good performance in a setting in which

- training and test sets are composed of ground programs taken from the *NP* and *Beyond NP* domains of the 3rd ASP Competition
- off-line features are computed, e.g. number of rules and atoms, ratio of horn rules and constraints
- CLASP, IDP, DLV, CMODELS are selected as ASP solvers
- the policy is learned with classification algorithms, e.g. decision rules, decision trees, nearest-neighbor

Enhancement to the basic, off-line approach: (MPR, 2014b)

- adaptation of the policy when it fails to give good prediction

- **ASP:**

- purely declarative programming paradigm
- **idea:** write a logic program s.t. its answer sets represent solutions
- can capture all problems at the second level of the polynomial hierarchy
- exploited in AI and real-world applications

- An ASP program Π is made of rules:

$$a_1 \vee \dots \vee a_n \text{ :- } b_1, \dots, b_k, \text{ not } b_{k+1}, \dots, \text{ not } b_m$$

- Answer Set Semantics:

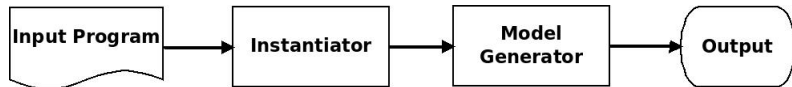
- consider the ground instantiation $P = \text{ground}(\Pi)$
- find a minimal model of the Gelfond-Lifschitz reduct of P

Evaluation of ASP programs



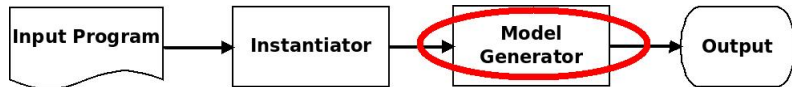
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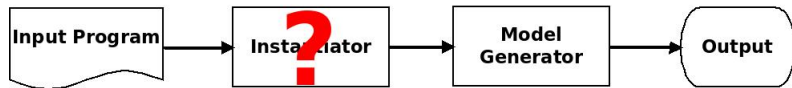
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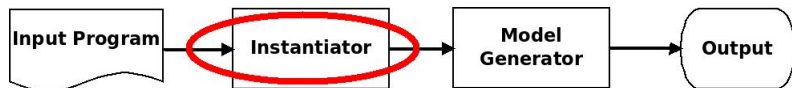
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What about the **Instantiator**?

Current contribution

Evaluation of ASP programs



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Current contribution

A first step toward the exploitation of automated algorithm selection techniques to the **Instantiator** (or, **grounder**).

Features and problems

Features:

- Problem size, balance and proximity to Horn features
- Presence of queries
- Maximum Strongly Connected Components size
- Features indicating if the program is recursive, tight, stratified
- ...

Features computed on instances of the P and NP domains **submitted** to the 3rd ASP Competition (**evaluated** instances have been discarded, and are used to test our solution).

Classification and model

- PART algorithm to automatically build an If-then-else decision list
 - Supervised classification algorithm
 - Patterns are the feature vectors
 - Classes (labels) are the grounders

Resulting model with DLV-G and GRINGO3 grounders

- DLV-G is usually preferable when
 - Dealing with queries
 - Program contain rules having large bodies (e.g., ≥ 4 literals) and the program has a simple structure (few components)
- GRINGO is usually preferable when
 - Recursive programs with many components
 - Most of the rules have a short body

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Automated grounder SELECTOR

- A feature extractor for non-ground programs
- A decision-making module implementing the model

Solver	Grounder	<i>P</i>		<i>NP</i>		Total	
		#	Time	#	Time	#	Time
CLASP	DLV-G	48	128.26	93	62.65	141	84.99
	GRINGO	35	97.21	72	32.69	107	53.80
	SELECTOR	48	70.94	95	59.64	143	63.43
CMODELS	DLV-G	46	130.47	86	82.42	132	99.16
	GRINGO	32	116.29	67	58.44	99	77.14
	SELECTOR	46	70.60	87	80.72	133	77.22
DLV	DLV-G	41	129.17	59	71.39	100	95.08
	GRINGO	31	107.89	37	28.53	68	64.71
	SELECTOR	41	71.26	59	69.50	100	70.22
IDP	DLV-G	43	136.54	92	71.13	135	91.96
	GRINGO	32	140.57	72	46.97	104	75.77
	SELECTOR	43	74.16	94	70.19	137	71.43

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Conclusion & Future Work

Both grounders and solvers are crucial for the performance of an ASP system

- a first step toward the exploitation of automated selection techniques to the grounding component

Our grounder selector improves the evaluation performance **independently from the solver** associated

Future Work

- Validate the results on domains of latest competitions
- Selector able to predict the best grounder+solver pair among a set of possible combinations

Other/more details at:

<https://www.mat.unical.it/~ricca/me-asp/>

Some references

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