Systems and Solving Techniques for Knowledge Representation

– Guess & Check –

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ASP Basics

ASP:

- $\mathsf{Datalog} \leftarrow \mathsf{done!}$
- + Default negation ← done!
- + Disjunction ← done!
- + Integrity Constraints done!
- + Weak Constraints ← done!
- + Aggregate atoms ← done!

How to program in ASP?

Programming methodology

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Programming methodology

The idea of ASP:

Write a program representing a computational problem

 \rightarrow i.e., such that answer sets correspond to solutions

- Use a solver to find solutions
- Programming Steps:
 - Model your domain
 - → Single out input/output predicates
 - Write a logic program modeling your problem
 - \rightarrow Use predicates representing relevant entities
 - ightarrow Hint: take input data separated from derived ones

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Direct Encodings when...

Use a "Direct" Encoding with Datalog rules for

• Polynomial Problems, etc.

Example (Reachability)

Problem: Find all nodes reachable from the others. **Input:** *edge*(_,_).

```
% X is reachable from Y if an edge (X,Y) exists reachable(X,Y) := edge(X,Y).
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```
% Reachability is transitive reachable(X, Y) :- reachable(X, Z), edge(Z, Y).
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Programming Methodology

Guess & Check & Optimize (GCO)

- Guess solutions \rightarrow using disjunctive rules
- Optimization problem?
- Specify Preference criteria \rightarrow using weak constraints

In other words...

- 2 constraints \rightarrow test solutions discarding unwanted ones
- (i) weak constraints \rightarrow single out optimal solutions

Programming Methodology

Guess & Check & Optimize (GCO)

- Guess solutions \rightarrow using disjunctive rules
- **2** Check admissible ones \rightarrow using strong constraints *Optimization problem?*

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Programming Methodology

Guess & Check & Optimize (GCO)

- Guess solutions \rightarrow using disjunctive rules
- Check admissible ones \rightarrow using strong constraints *Optimization problem*?
- Specify Preference criteria \rightarrow using weak constraints

In other words...

- $\textbf{0} \ \text{disjunctive rules} \rightarrow \text{generate candidate solutions}$
- 2 constraints \rightarrow test solutions discarding unwanted ones
- \odot weak constraints \rightarrow single out optimal solutions

Guess and Check (Example 1)

Example (Group Assignments)

Problem: We want to partition a set of persons in two groups, while avoiding that father and children belong to the same group. Input: persons and fathers are represented by person(_) and father(_,_).

% a disjunctive rule to "guess" all the possible assignments

group(P, 1) | group(P, 2) := person(P).

% a constraint to discard unwanted solutions % i.e., father and children cannot belong to the same group

:- group(P1, G), group(P2, G), father(P1, P2).

...so how does it work really?

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Guessing part explained

Consider: group(P, 1) | group(P, 2) := person(P).

If the input is: *person(john)*. *person(joe)*. *father(john, joe)*.

Then, the answer set of this single-rule program are:

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Consider: group(P, 1) | group(P, 2) := person(P). := group(P1, G), group(P2, G), father(P1, P2).

If the input is: *person(john)*. *person(joe)*. *father(john, joe)*. The answer sets are:

{person(john), person(joe), father(john, joe), group(john, 1), group(joe, 2)}
{person(john), person(joe), father(john, joe), group(john, 2), group(joe, 1)}

G&C = Define search space + specify desired solutions

Guess and Check (Example 2)

Example (3-col)

Problem: Given a graph assign one color out of 3 colors to each node such that two adjacent nodes have always different colors.
Input: a Graph is represented by node(_) and edge(_,_).

% guess a coloring for the nodes (r) $col(X, red) \mid col(X, yellow) \mid col(X, green) := node(X).$

% discard colorings where adjacent nodes have the same color (c) :- edge(X, Y), col(X, C), col(Y, C).

% NB: answer sets are subset minimal \rightarrow only one color per node

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Guess and Check (Example 3)

```
Problem: Find a path in a Graph beginning at the starting node which
contains all nodes of the graph.
Input: node(_) and edge(_,_), and start(_).
    % Guess a path
                                                          Guess
    inPath(X, Y) \mid outPath(X, Y) := edge(X, Y).
                                                          Check
                                                          Aux. Rules
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Input: node(_) and edge(_,_), and start(_).
    % Guess a path
                                                          Guess
    inPath(X, Y) \mid outPath(X, Y) := edge(X, Y).
    % A node can be reached only once
    :- inPath(X, Y), inPath(X, Y1), Y \ll Y1.
                                                          Check
    :- inPath(X, Y), inPath(X1, Y), X \ll X1.
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    % All nodes must be reached
    :- node(X), not reached(X).
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    :- inPath(X, Y), inPath(X1, Y), X \ll X1.
    % All nodes must be reached
    :- node(X), not reached(X).
    % The path is not cyclic
    :- inPath(X, Y), start(Y).
                                                          Aux. Rules
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    % All nodes must be reached
    :- node(X), not reached(X).
    % The path is not cyclic
    :- inPath(X, Y), start(Y).
    reached(X) := reached(Y), inPath(Y, X).
                                                          Aux. Rules
    reached(X) := start(X).
```

Guess, Check and Optimize (Example 4)

Example (Traveling Salesman Person)

Problem: Find a path of minimum length in a Weighted Graph beginning at the starting node which contains all nodes of the graph. **Input:** *node*(_) and *edge*(_, _, _), and *start*(_). % Guess a path Guess $inPath(X, Y) \mid outPath(X, Y) := edge(X, Y,).$ Check Aux. Rules Optimize

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- $\sim\,$ Abstract solvers for disjunctive ASP with bj and learning
- $\sim\,$ Abstract solvers for cautious ASP reas. with bj and lear
- × Abstract solvers for ASP with aggregates
- × Abstract solvers for finding "optimal" ASP solutions

And what's about abstract solvers for this lecture?

$\sim\,$ Abstract solvers for disjunctive ASP with bj and learning

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Thanks to Francesco Ricca for a preliminary version of these slides